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Robust and scalable prescriptive analytics for the resilience of interdependent networks

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Chair on Risk and Resilience of Complex Systems

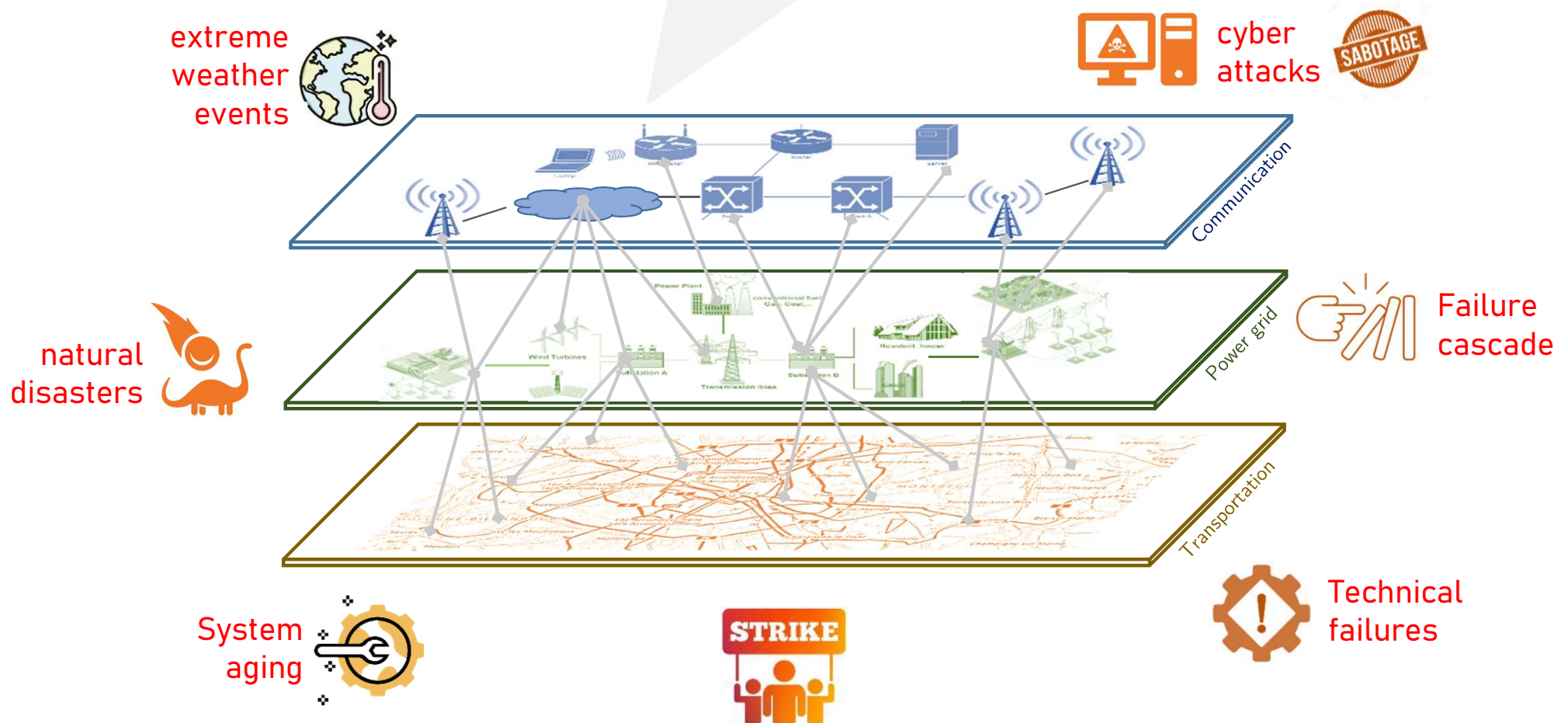
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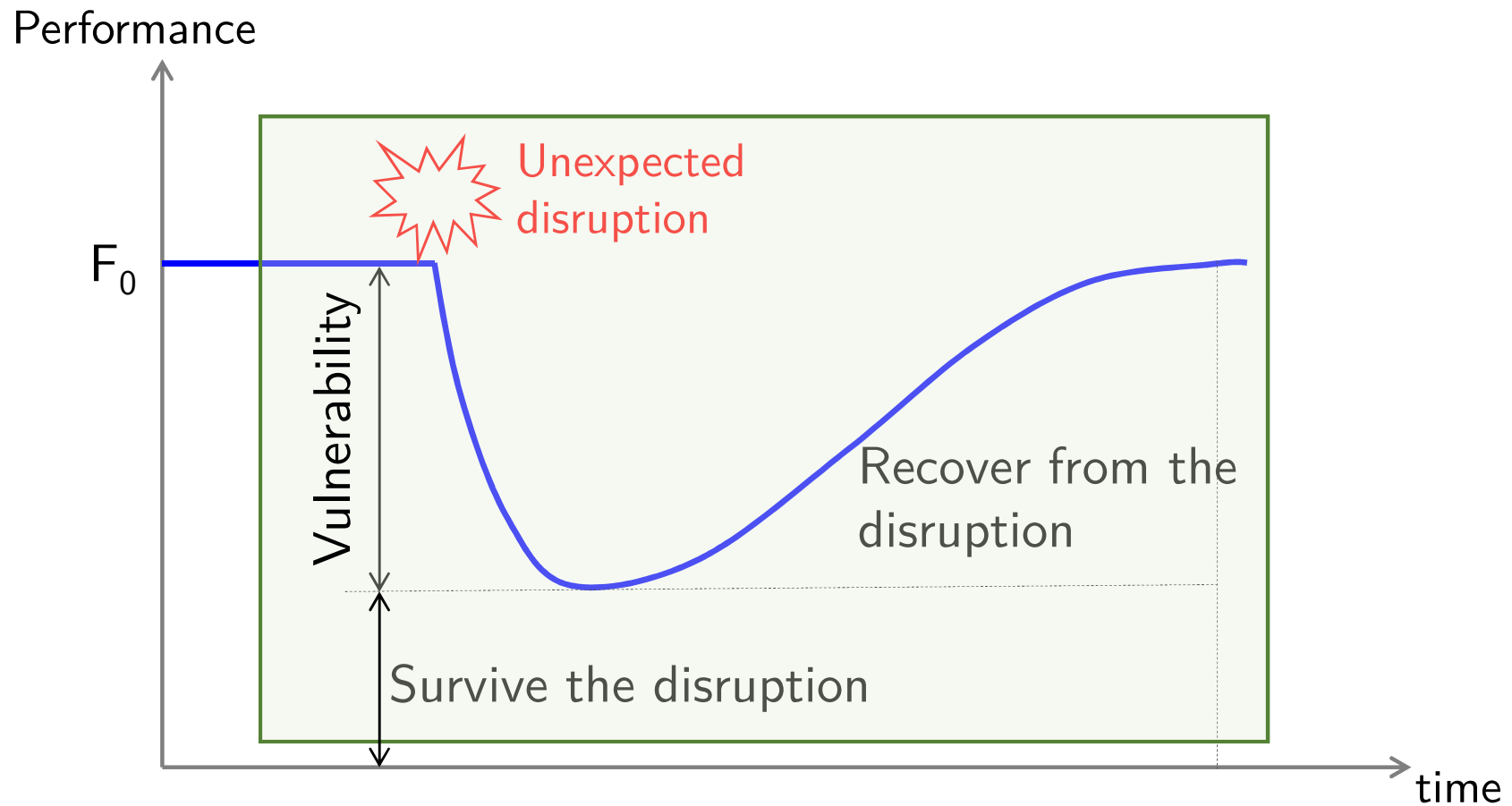
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RRCS Journée de Chaire, 27/09/2023

How to make our systems
(more) resilient?

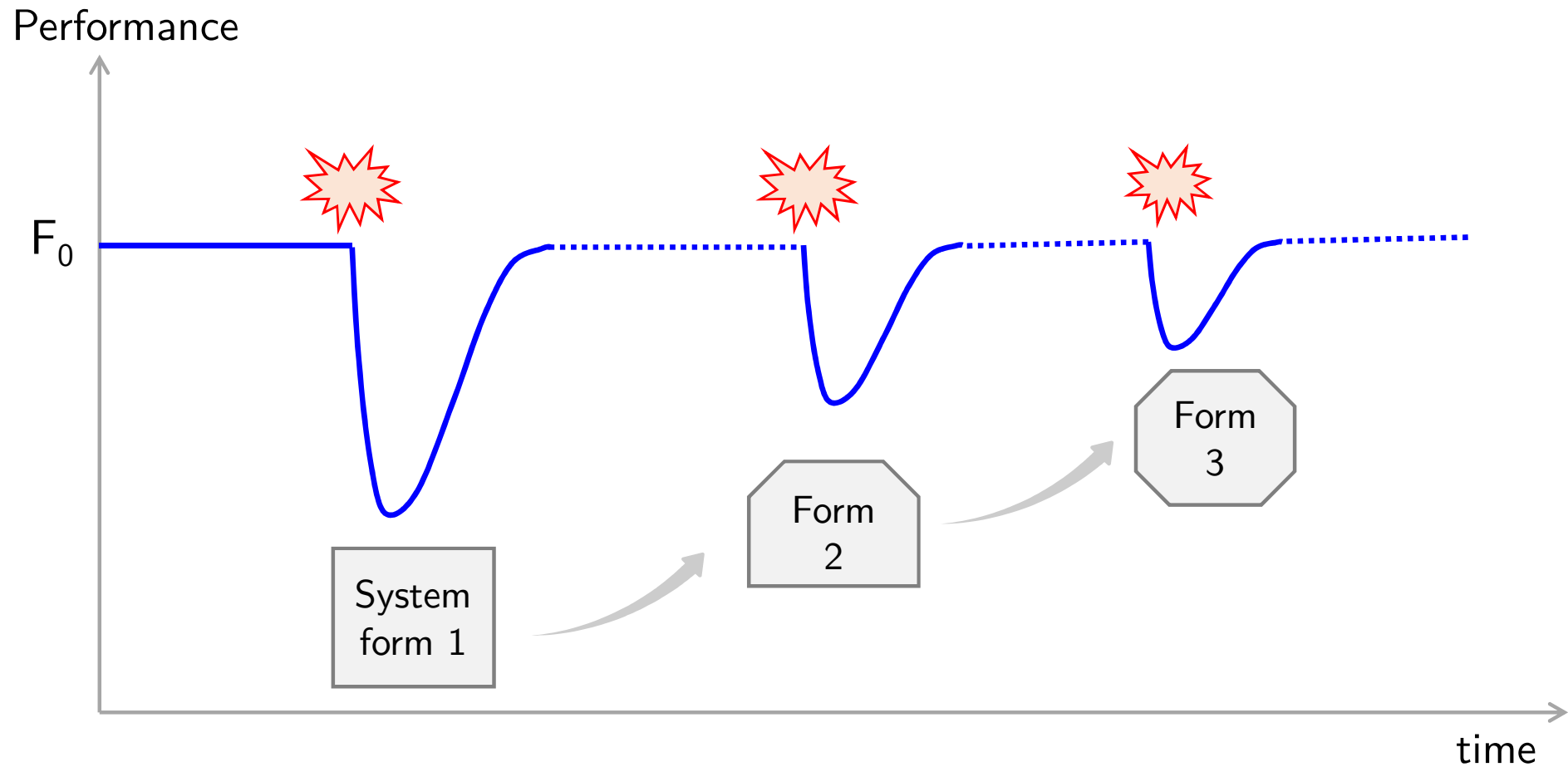


Resilience: symptom-wise



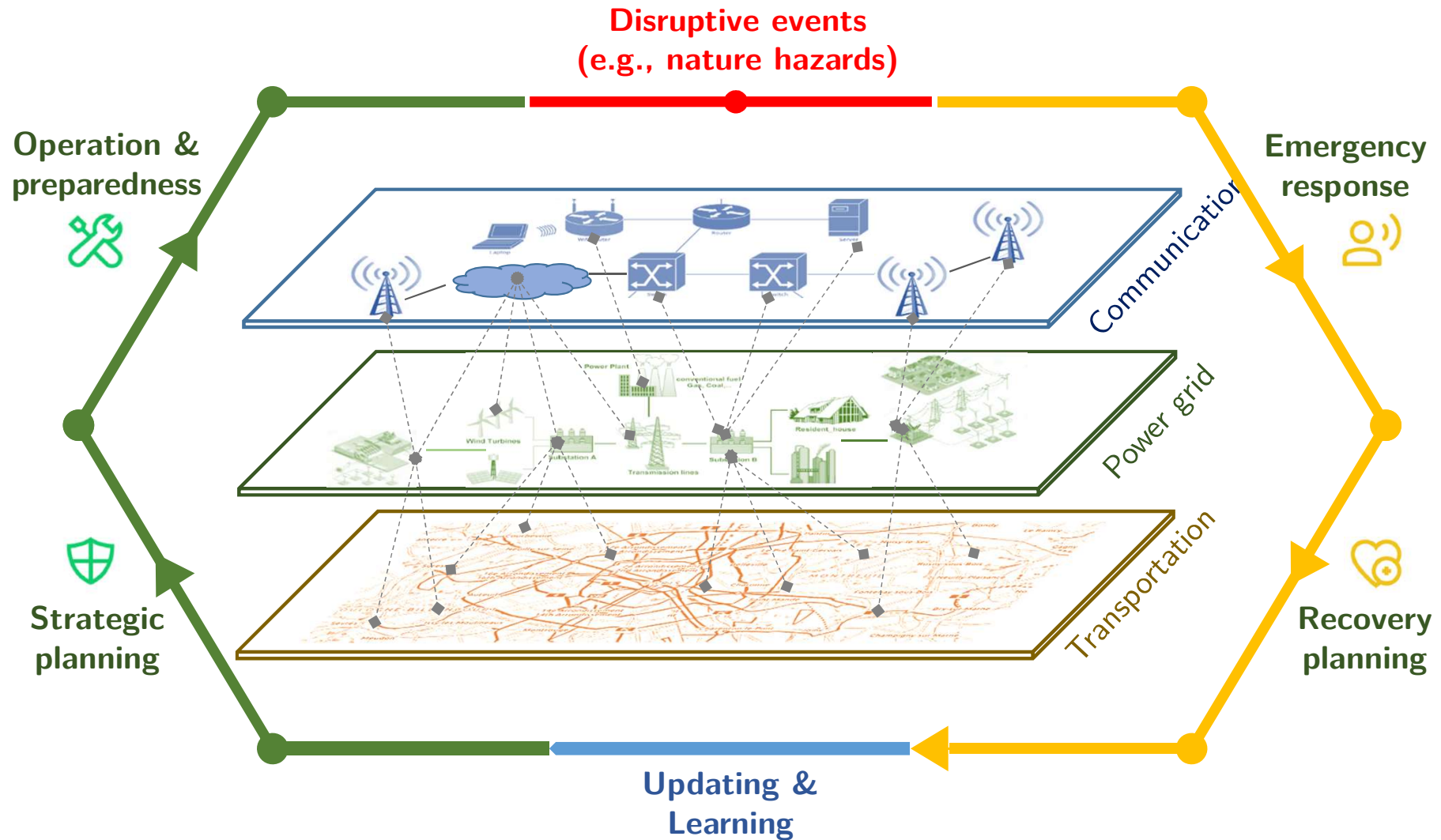
survivability + recoverability

Resilience: symptom-wise



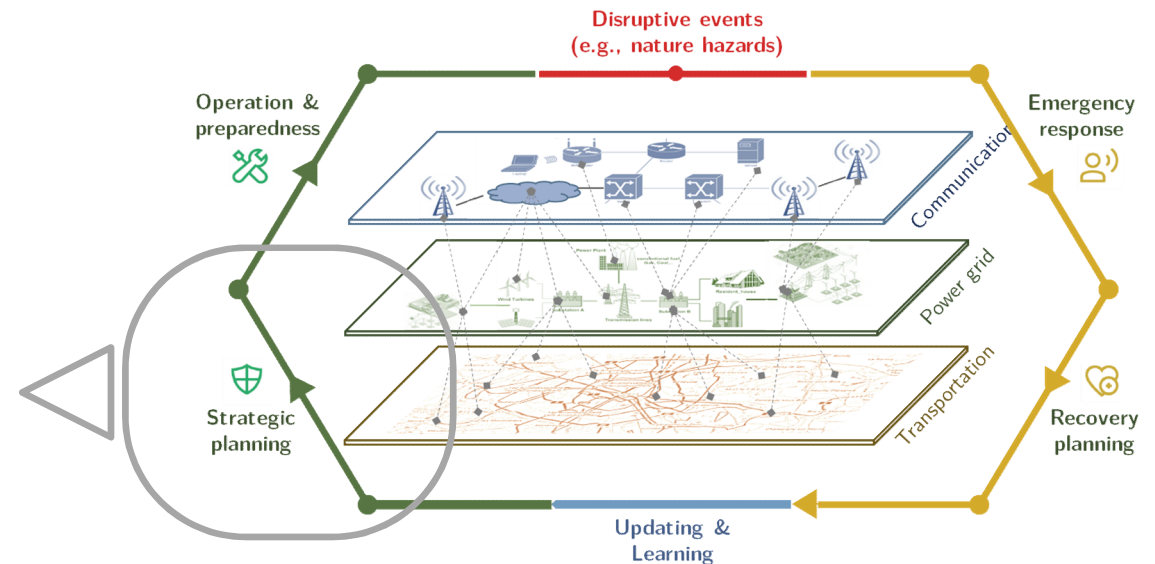
survivability + recoverability
+ adaptive/transformative capability

Resilience: prescription-wise



Consider **resilience** when making decisions that have **mid-/long-term effects**?

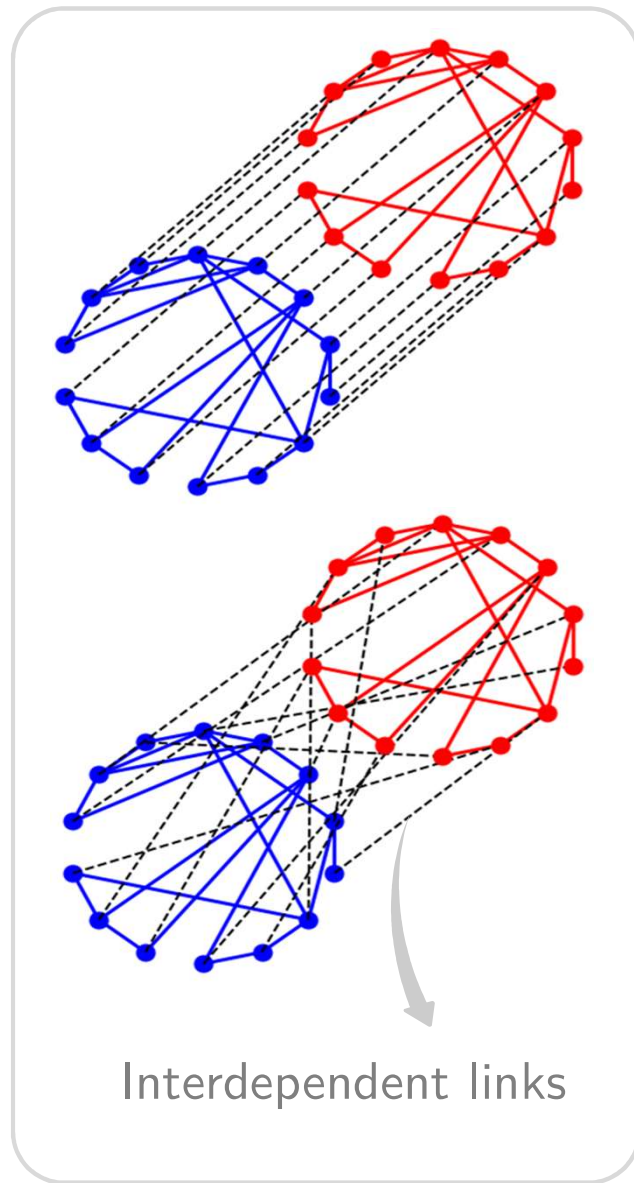
- structure (re)design
- integration of new technologies
- maintenance strategy



Decision-making under uncertainty, key challenges:

- deep **uncertainty** of future risk scenarios
- need of having **robust** solutions & computational tractability

Example: coupling interface design



- ↑ Survivability under **uncertain** components failures
- ↑ performance & ↓ cost in normal operation

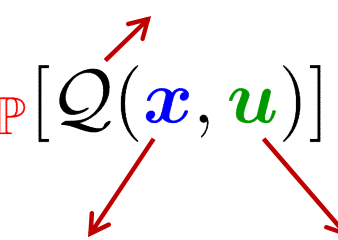
Bellè, A., Abdin, A. F., Fang, Y. P., Zeng, Z., & Barros, A. (2023). A data-driven distributionally robust approach for the optimal coupling of interdependent critical infrastructures under random failures. *European Journal of Operational Research*, 309(2), 872-889.

Stochastic program (SP) & Robust optimization (RO)

Recourse function


$$\text{SP} : \max_{\mathbf{x} \in \mathbb{X}} \mathbb{E}_{\mathbb{P}}[Q(\mathbf{x}, \mathbf{u})]$$

Design variables Failure scenario



$$\text{RO} : \max_{\mathbf{x} \in \mathbb{X}} \min_{\mathbf{u} \in U} Q(\mathbf{x}, \mathbf{u})$$

Uncertainty set: all feasible failure scenarios

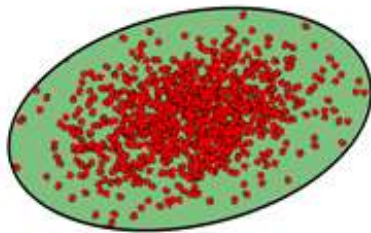


- ▷ Probability distribution of the set of all feasible failure scenarios
- ▷ Difficult to estimate due to lack of data & environment variability
- ▷ No need to estimate the **probabilities** of failure scenarios
- ▷ Too conservative/costly

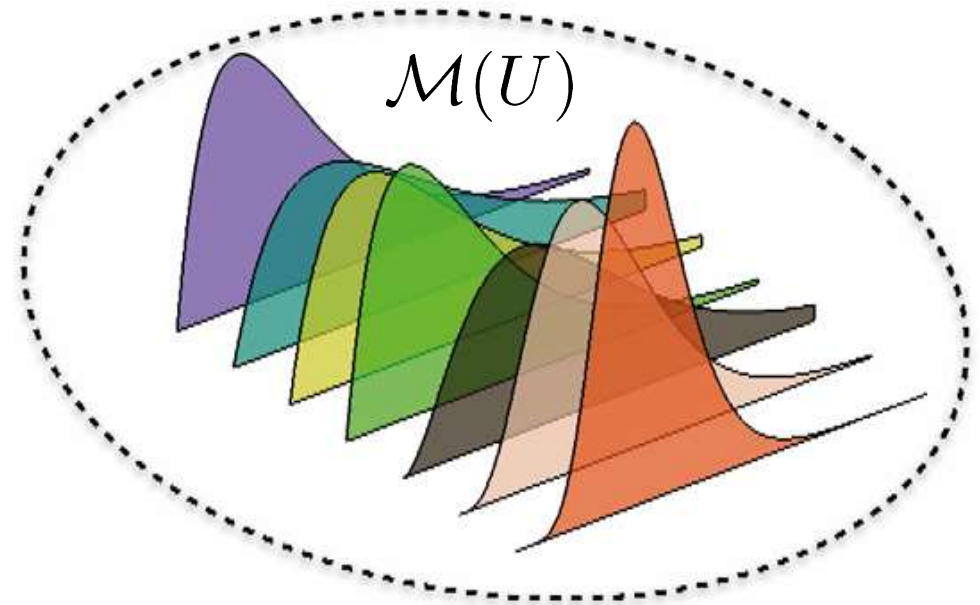
Distributionally robust approach

$$\text{SP} : \max_{\mathbf{x} \in \mathbb{X}} \mathbb{E}_{\mathbb{P}} [\mathcal{Q}(\mathbf{x}, \mathbf{u})]$$

$$\text{DRO} : \max_{\mathbf{x} \in \mathbb{X}} \min_{\mathbb{P} \in \mathcal{M}(U)} \mathbb{E}_{\mathbb{P}} [\mathcal{Q}(\mathbf{x}, \mathbf{u})]$$



Empirical failure data



- Ambiguity set

$$\mathcal{M}(U) = \{\mathbb{P} \in \mathcal{P}(U) : \mathbf{0} \leq \mathbb{E}[1 - \mathbf{u}] \leq \boldsymbol{\pi}^{max}\}$$

$$U = \{\mathbf{u} \mid \mathbf{u} \in \{0, 1\}^N, \|\mathbf{u}\|_1 \geq N - k\}$$

- ▷ Set of multinomial distributions on the set of feasible failure scenarios
- ▷ Upper bound on the marginal probability of component failure

for optimal coupling interface design of IPGNs

$$\max_{\substack{\mathbf{h}^0, \boldsymbol{\delta}^0 \in \{0,1\}^{N_d} \\ \mathbf{y} \in \{0,1\}^{N_e}}} \min_{\mathbb{P} \in \mathcal{M}} \mathbb{E}_{\mathbb{P}} [\mathcal{Q}(\mathbf{y}, \boldsymbol{\xi})]$$

$$\text{s.t.} \quad \sum_{j \in V_{PN}} y_{ij}^1 \leq 1, \quad \forall i \in V_{GN}$$

$$\sum_{j \in V_{GN}} y_{ij}^2 \leq 1, \quad \forall i \in V_{PN}$$

$$\sum_{\substack{i \in V_{GN} \\ j \in V_{PN}}} y_{ij}^1 d_{ij}^{km} c_{km}^1 + \sum_{\substack{i \in V_{PN} \\ j \in V_{GN}}} y_{ij}^2 d_{ji}^{km} c_{km}^2 \leq B_c$$

$$\mathbf{R}^0 \mathbf{h}^0 \leq \mathbf{q}^0 - \mathbf{H}^0 \mathbf{y} - \mathbf{W}^0 \boldsymbol{\delta}^0 - \mathbf{y}^T \mathbf{D}^0 \boldsymbol{\delta}^0 - \mathbf{y}^T \mathbf{G}^0 \boldsymbol{\delta}^0 \mathbf{c}^{0T} \mathbf{y}$$

$$\mathbf{b}^T \mathbf{h}^0 \geq 1$$

$$\begin{aligned} & \max_{\mathbf{h}, \boldsymbol{\delta} \in \{0,1\}^{N_d}} \mathbf{b}^T \mathbf{h} \\ & \text{s.t.} \\ & \mathbf{R} \mathbf{h} \leq \mathbf{q} - \mathbf{T} \mathbf{u} - \mathbf{H} \mathbf{y} - \mathbf{W} \boldsymbol{\delta} - \mathbf{y}^T \mathbf{D} \boldsymbol{\delta} - \mathbf{y}^T \mathbf{G} \boldsymbol{\delta} \mathbf{c}^T \mathbf{y} \end{aligned}$$

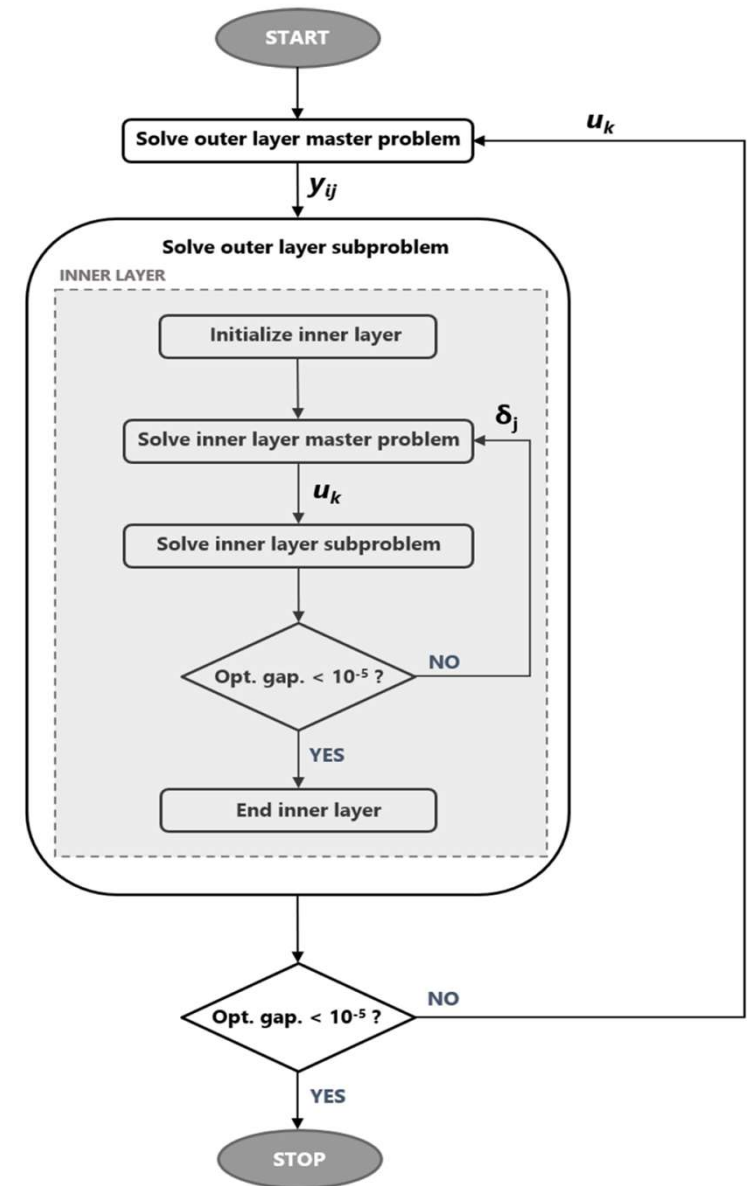
$$\max_{\mathbf{y} \in \mathcal{Y}} \min_{\mathbf{P} \in \mathcal{M}(\mathcal{U})} \mathbb{E}_{\mathbf{P}} [Q(\mathbf{y}, \mathbf{u})]$$

Proposition 1: dual counterpart

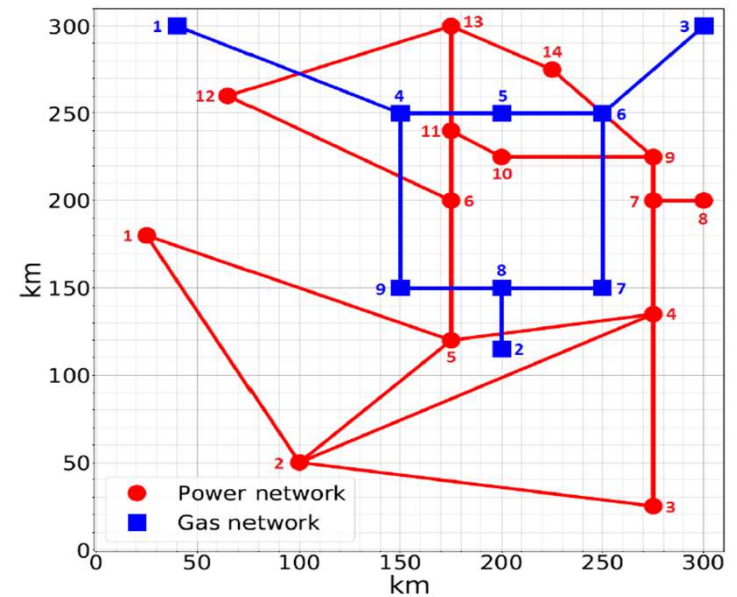
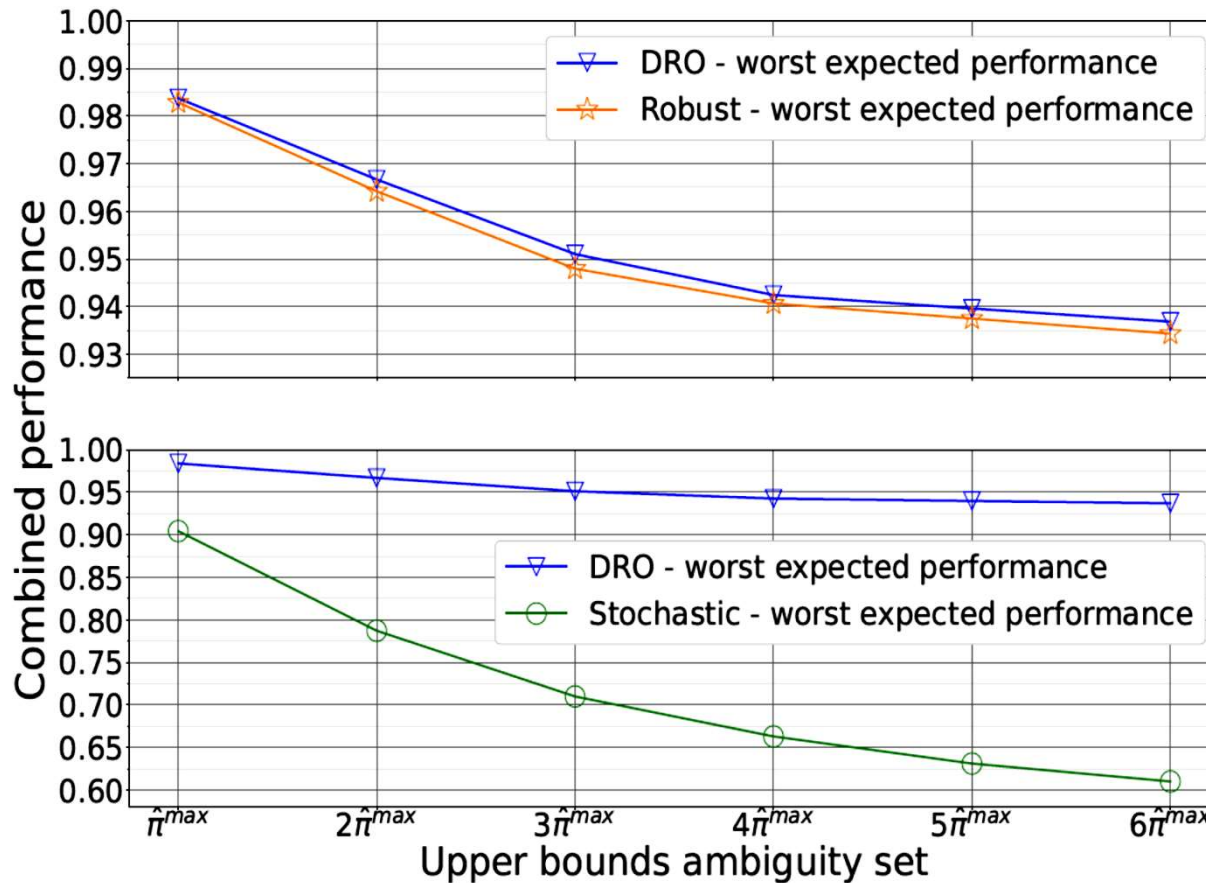
$$\max_{\mathbf{y} \in \mathcal{Y}} \min_{\mathbf{u} \in \mathcal{U}} Q(\mathbf{y}, \mathbf{u}) + \sum_{n \in \mathcal{N}} \beta_n (1 - u_n - \pi_n^{max})$$

Proposition 2: Equivalent monolithic MILP

Nested column-constraint-generation algorithm

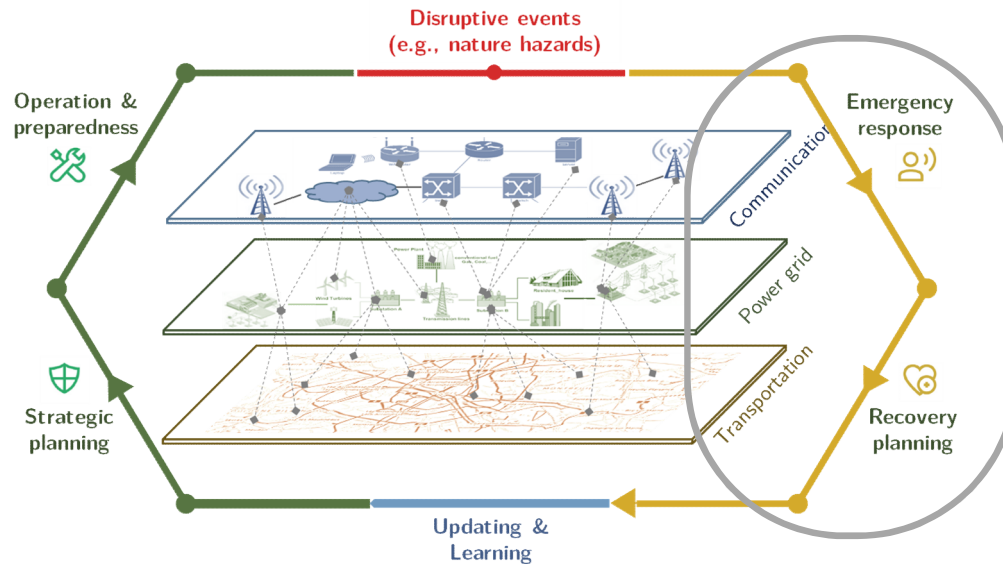


Key results



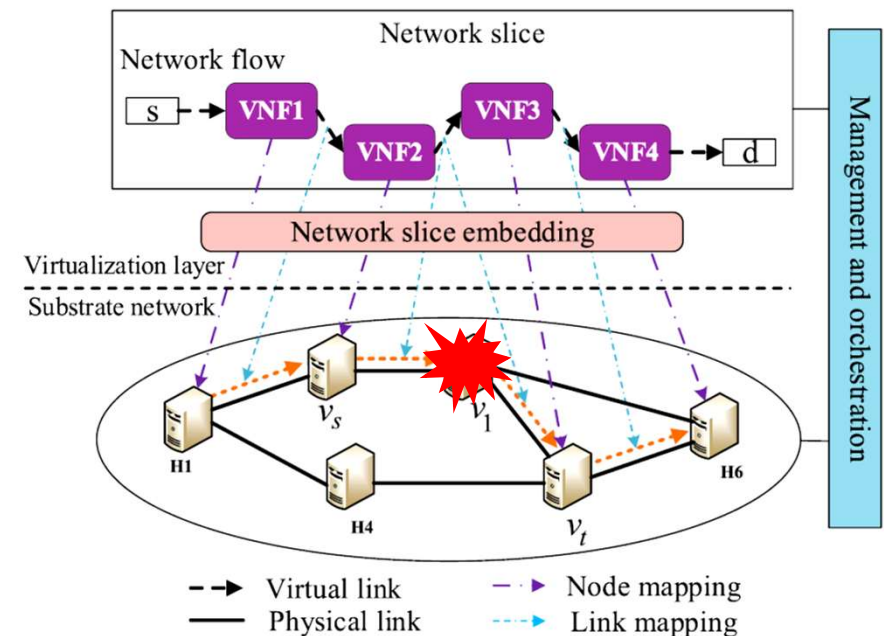
- ▷ RO solutions are suboptimal in terms of their expected performance in the worst-case distribution \mathbb{P}^{\star}
- ▷ SP solutions perform very poorly when tested under \mathbb{P}^{\star}

- Power grid **protection investment** with endogenous uncertainty
Bellè, A., Fang, Y. P., Zeng, Z., & Barros, A. (2022). *IFAC-PapersOnLine*, 55(16), 122-127.
- Optimal **siting & sizing of DESs** for grid resilience against wind storms
Yin, Z., Fang, C., Yang, H., **Fang, Y.**, & Xie, M. (2023). *Risk Analysis*.
- Robust **day-ahead flight planning in ATM** considering extreme weather events
Hao, B., Cai, K., **Fang, Y. P.**, Fadil, A., & Feng, D. (2021, October). In *2021 IEEE/AIAA 40th Digital Avionics Systems Conference (DASC)* (pp. 1-7). IEEE.

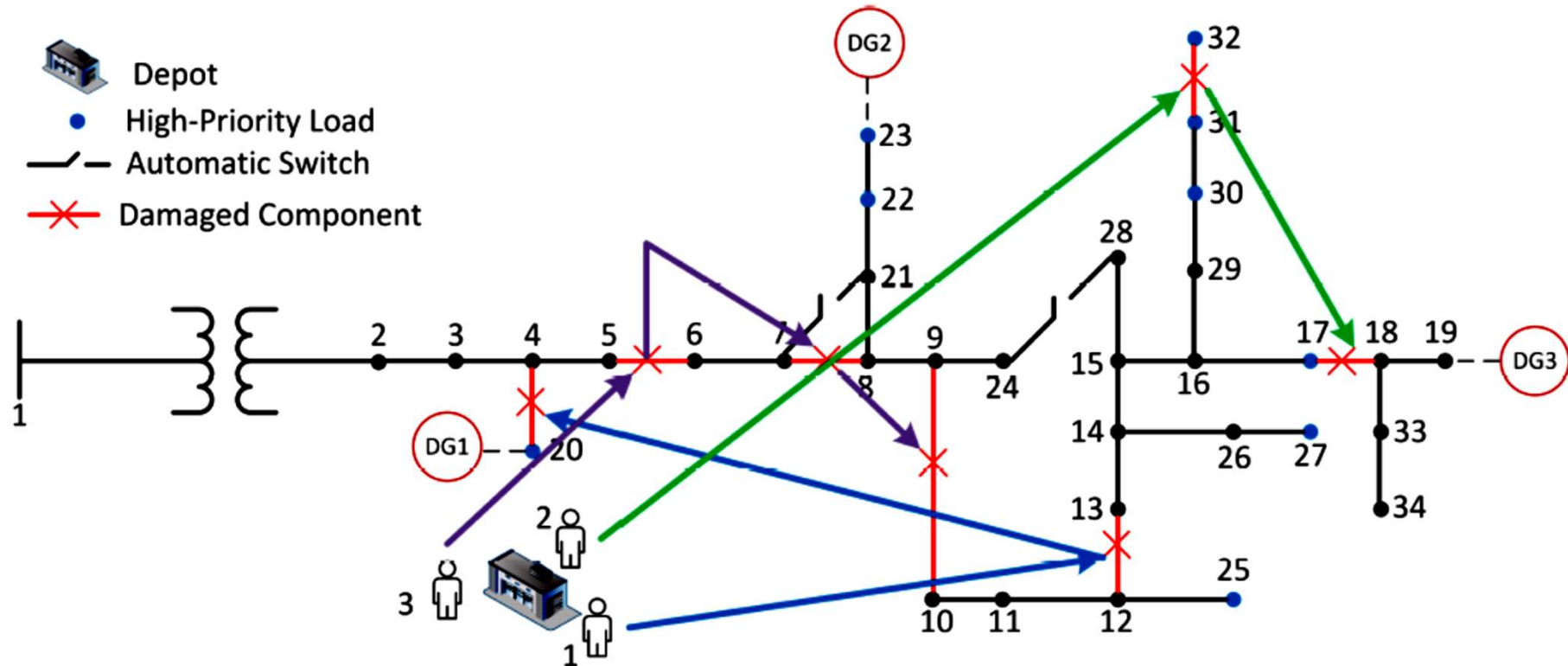


Mitigate service loss and speed up system recovery by leveraging flexibility/maintenance resources

- Examples:
 - Reconfiguration of network slicing in 5G
 - Integrated reconfiguration and recovery in power distribution grids
 - ...



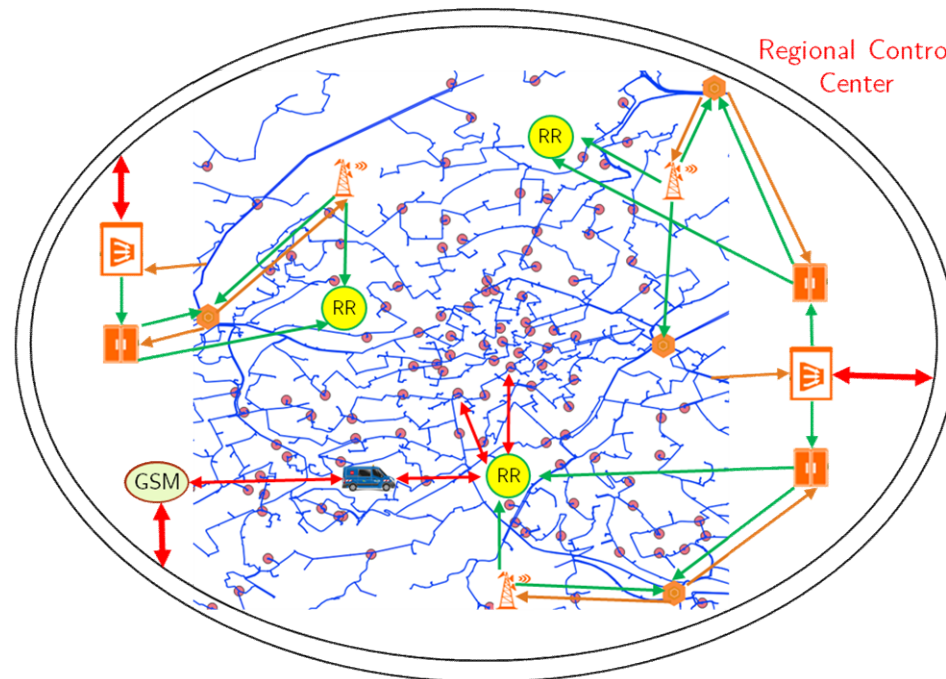
Example: distribution grid recovery



- Flexibility resources: automatic/manual switches → control decisions), DGs → allocation
- Maintenance resources: repair crews → scheduling

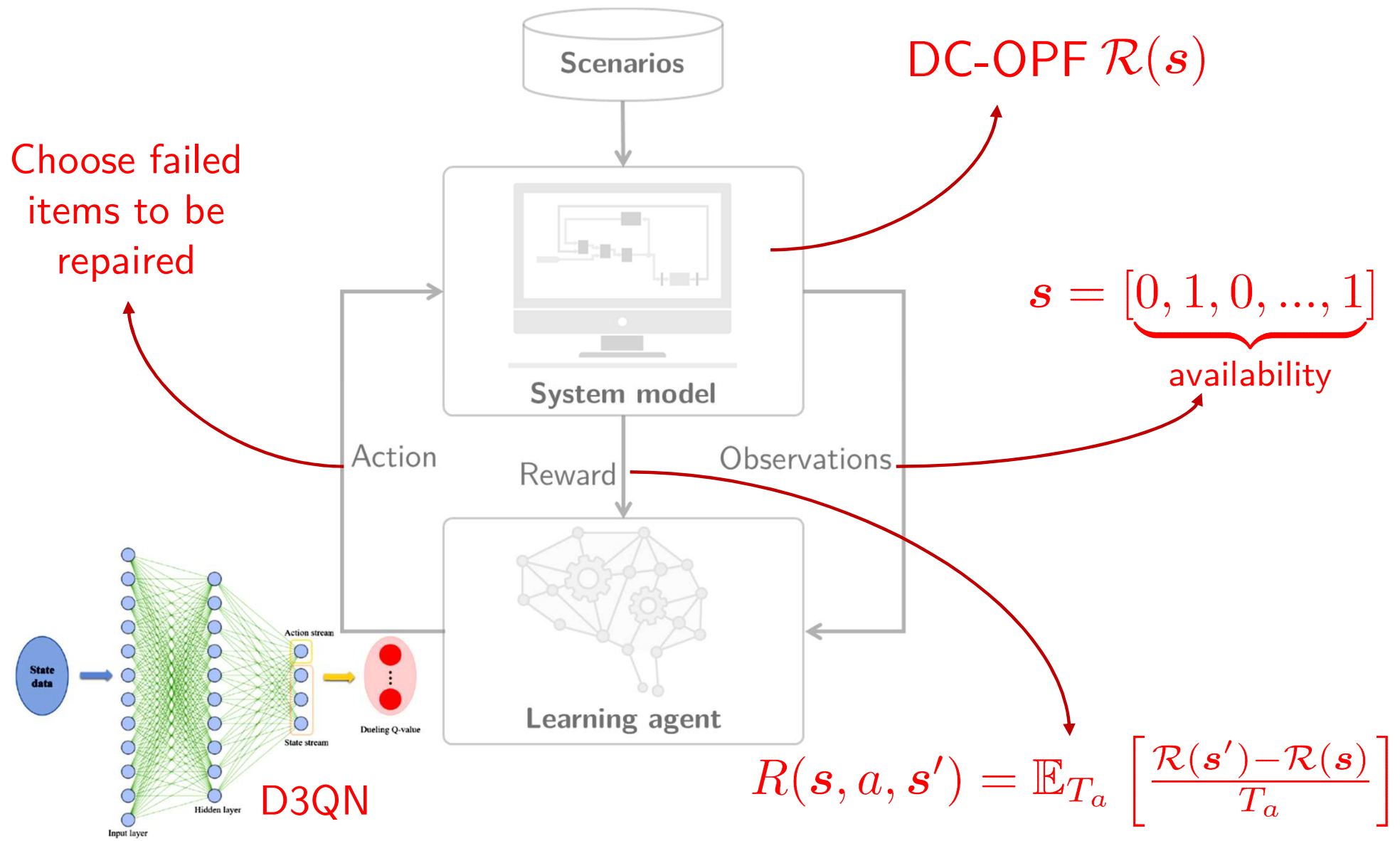
- MILP for **communication-aware** restoration (Belaïd et al. 2023)

Network Setting



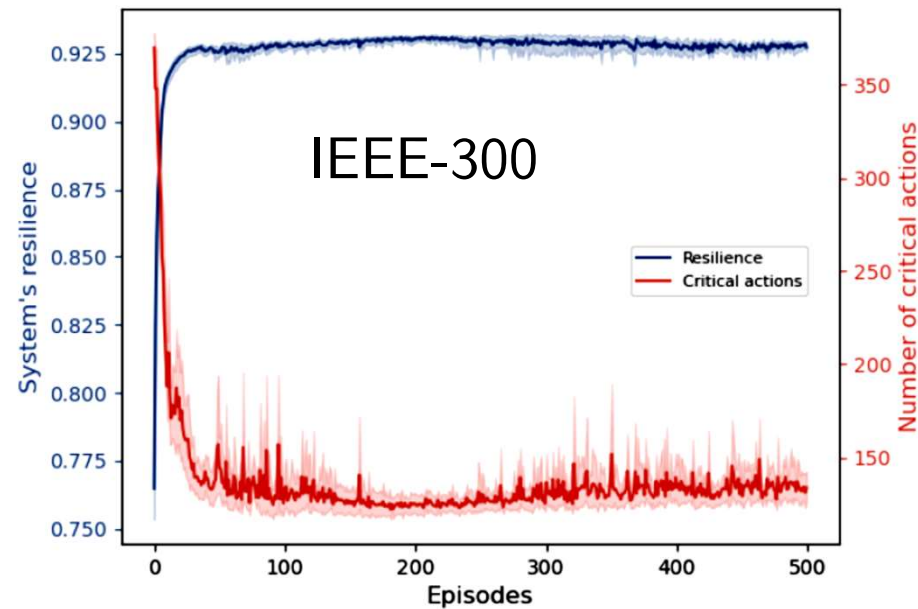
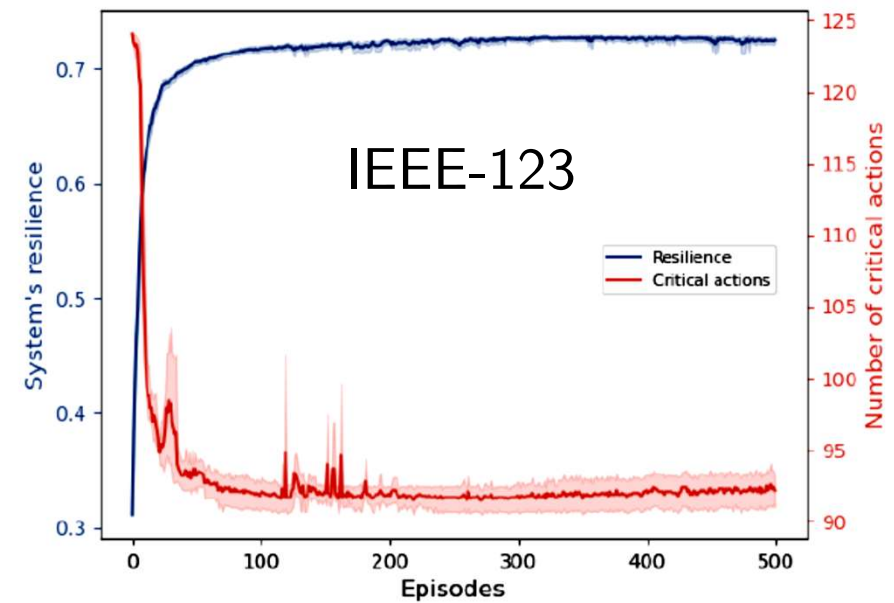
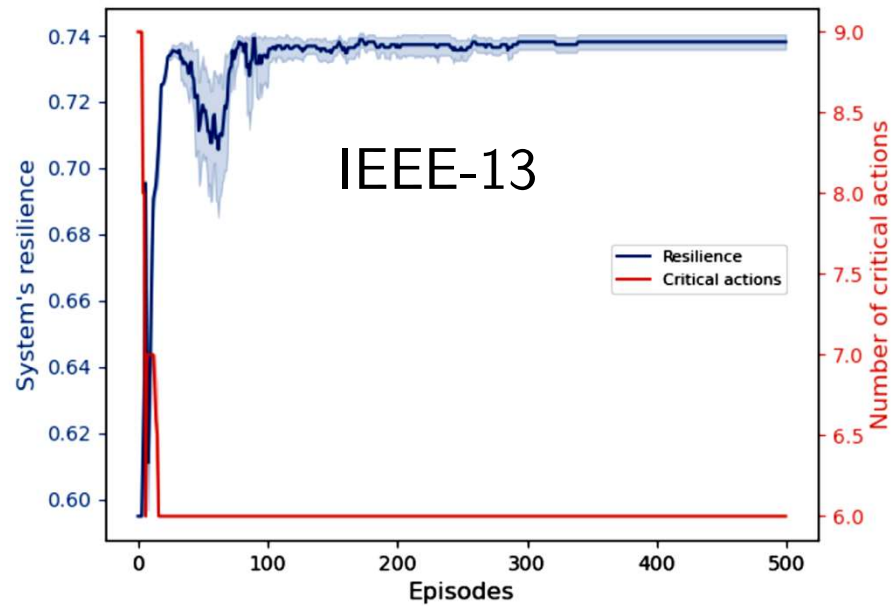
- Stochastic MILP to consider **uncertain times** of individual repair tasks (Fang and Sansavini, 2019)
- Key challenge: combinatorial nature v.s. highly time-critical in ex-post stage → scalable method

DRL for scalability



Z.-Y. Yin, C. Fang, Y.-P. Fang, M. Xie. (2023) "An optimization-driven deep reinforcement learning framework for distribution grid recovery planning with large action space"

Key results



Trained DRL (D3QN & DDQN) vs. SO

Failure scenario	System	Method	Average CR	Time
50% damaged	13-node	D3QN	85.29%	<1s
		DDQN	85.29%	<1s
		SO	89.29%	<1s
	123-node	D3QN	76.72%	1.06s
		DDQN	75.79%	1.71s
		SO	74.98%	1h
	300-node	D3QN	95.25%	5.13s
		DDQN	93.79%	5.32s
		SO	None	None

- ▷ Near optimal performance with much less computational time

II. Ongoing projects and opportunities



Pascal Quach

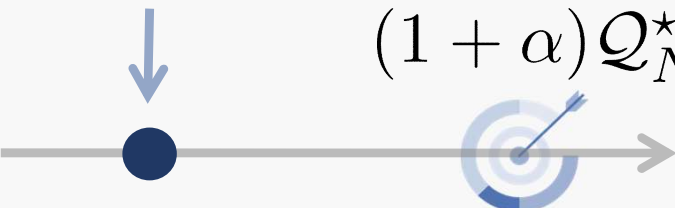
Stochastic optimization for the resilience of networked infrastructures against climate change, ANR JCJC Thesis

- Integrate historical & predicted data
- Compare/unify different approaches: RO & DRO & **Robust Satisficing**
- Develop tailored model & algorithm for energy systems (and other systems?)

$$Q_N^* = \min_{x \in \mathbb{X}} \mathbb{E}_{\mathbb{P}^N} [Q(x, \xi)]$$

↓

$(1 + \alpha) Q_N^*$



$$\begin{aligned} & \max_{x \in \mathbb{X}} \epsilon \\ & \text{s.t. } \mathbb{E}_{\mathbb{P}} [Q(x, \xi)] \leq (1 + \alpha) Q_N^*, \\ & \quad \forall \mathbb{P} \in \hat{\mathcal{P}}_N(\epsilon) \end{aligned}$$



Zhuojun Xie

Decision-focused learning and optimization for resilient system design and operation, CSC Thesis

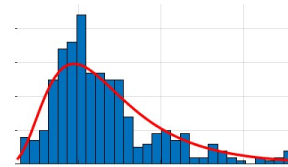
(x_i, y_i)

$\hat{y} = f(x; \theta)$

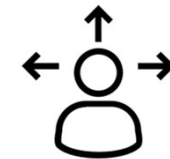
$z^*(\hat{y}) = \arg \max_{z \in Z(\hat{y})} g(z; \hat{y})$



Data



Estimation/Prediction



Decision-making/Optimize

Predict: RUL (Days)



	WT1	WT2
Ground truth	100	100
Pred. 1	110	90
Pred. 2	90	90
Pred. 3	110	110

Optimize: maintenance time to minimize cost

10k (ship icon) + 10k (wrench icon) + 30k (gear icon) = 60k

2x 10k (ship icon) + 2x 10k (wrench icon) = 30k

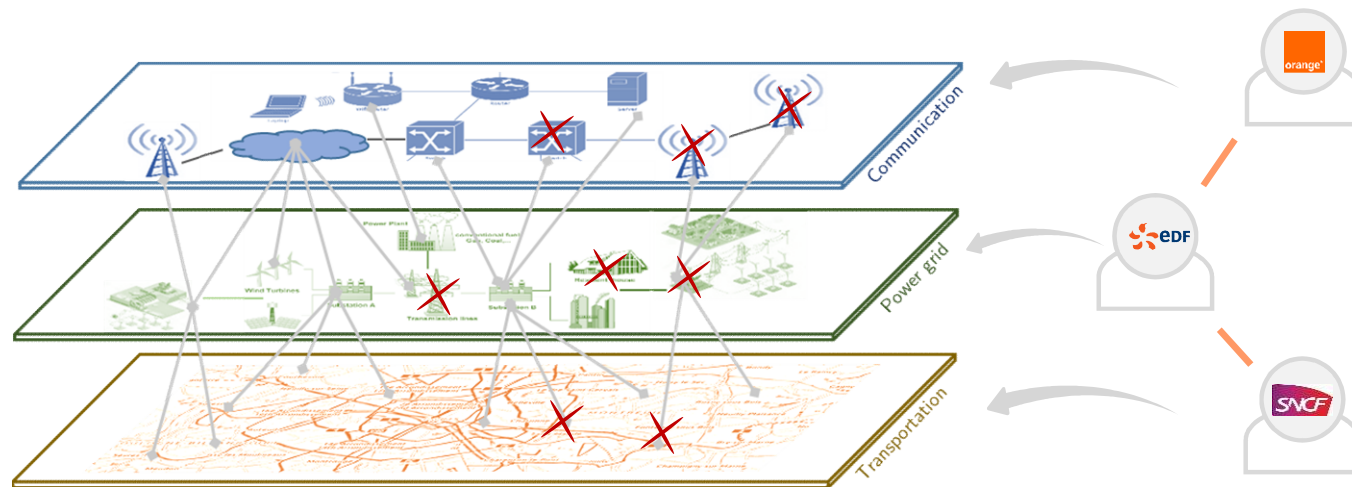
1x 10k (ship icon) + 2x 30k (gear icon) = 70k

Decision awareness in learning could be of high value!

Modelling aspects:

- Failure state *not fully known*, e.g., blocked/ damaged roads / failure in dependent systems; *Exploration takes resources* (e.g., drone inspection)
- *Decentralized* response & recovery planning with multiple operators

Postdoc to
be
recruited,
ANR JCJC

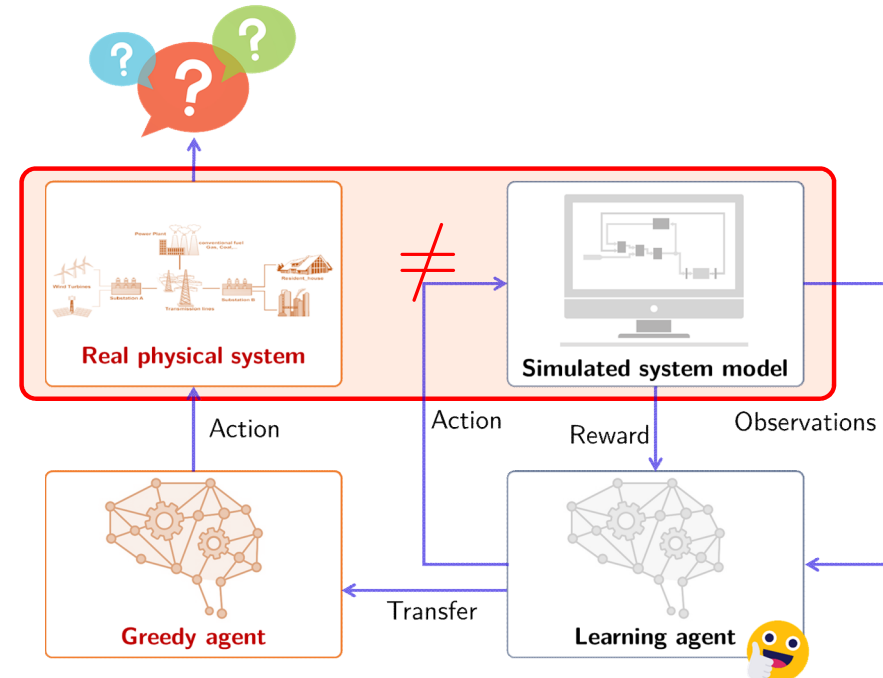


Wang, H., Fang, Y. P., & Zio, E. (2022). Resilience-oriented optimal post-disruption reconfiguration for coupled traffic-power systems. *Reliability Engineering & System Safety*, 222, 108408.

Algorithmic: learning robustness and interpretability

- **Trustfulness** in DRL

- *Simulation-to-reality gap*: distributional RL with risk-averse (Dulac-Arnold et al. 2019)
- *Safety*: constrained DRL incorporating domain-expert knowledge in training (Corsi et al. 2022)



- **Interpretability:**

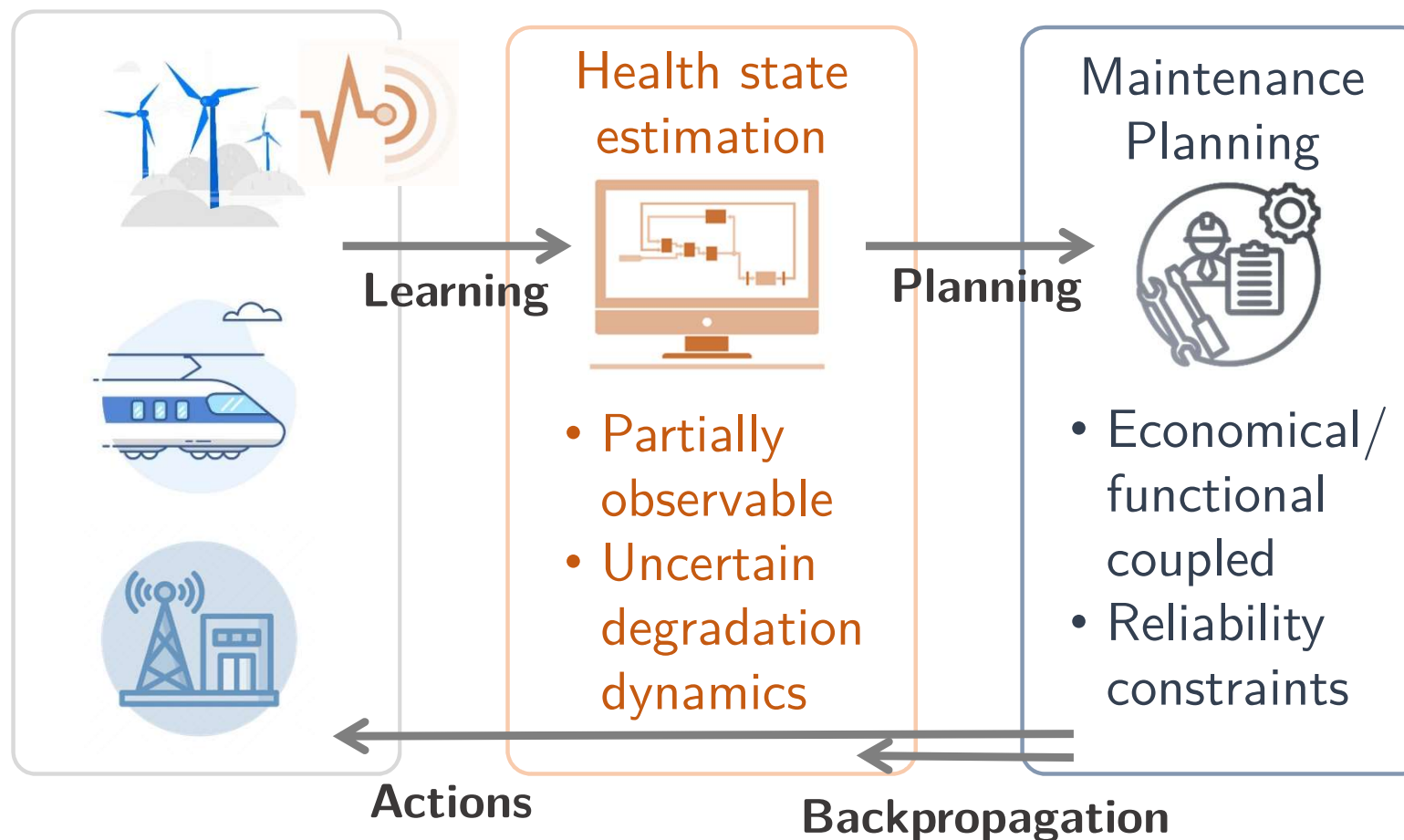
- More interpretable model in RL, e.g., tree, rule-based
- Visualization, attention/saliency maps...

Updating and learning

Integrated machine learning and optimization for dynamic decision-making in continuously monitored systems, RRCS Chair Thesis, 10/2023



Zehui Xuan



- Systemic roadmaps to map from symptoms to prescriptive actions?



- Resilience cost models: cost sharing/allocation

Thanks for your attention!



Chair Risk and Resilience of Complex Systems

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